

## NUMERICAL SOLUTION OF FREDHOLM INTEGRAL EQUATION OF THE SECOND KIND BY GENERAL LEGENDRE WAVELETS

XING TAO WANG AND YUAN MIN LI

Department of Mathematics  
Harbin Institute of Technology  
No. 92, West Da-Zhi Street, Harbin 150001, P. R. China  
xingtao@hit.edu.cn

Received October 2010; revised February 2011

**ABSTRACT.** *A general Legendre wavelets method is applied to Fredholm integral equation of the second kind. Using the general operational matrix of integration we approximate the solution of Fredholm integral equation of the second kind by general Legendre wavelets. Numerical examples are illustrated.*

**Keywords:** General Legendre wavelets, Fredholm integral equation, Numerical solution

1. **Introduction.** It is known that some boundary value problems can be transformed into Fredholm integral equations. For example, the boundary value problem

$$\frac{d^2x}{dt^2} + \lambda x = \varphi(t), \quad x(0) = x(1) = 0$$

can be transformed into the Fredholm integral equation of the second kind

$$x(t) = \lambda \int_0^1 K(t, s)x(s)ds + u(t), \quad t \in [0, 1],$$

where

$$K(t, s) = \begin{cases} s(1-t), & 0 \leq s \leq t, \\ t(1-s), & t < s \leq 1, \end{cases} \quad u(t) = - \int_0^1 t(1-s)\varphi(s)ds.$$

It is seen that Fredholm integral equations may be applied to boundary value problems in practice. It is known that the analytic solutions of Fredholm integral equations are obtained difficultly. There are different methods to approximate the solutions of Fredholm integral equations. Wavelets theory has been applied in a wide range of engineering disciplines [1]. A Legendre wavelet method for solving nonlinear optimal control problems with inequality constraints was presented in [2]. The authors in [3] used this Legendre wavelet method to solve the nonlinear Volterra-Fredholm integral equations. By piecewise constant two-dimensional block-pulse functions and their operational matrix of integration, two-dimensional first kind integral equations were reduced to a lower triangular system in [4]. Orthogonal functions or polynomials, such as Walsh [5], block-pulse functions [6], Chebyshev [7], Laguerre [8], Legendre [9], Fourier [10] and hybrid functions [11, 12, 13] are developed for solving various systems. Now we use the general Legendre wavelets to solve Fredholm integral equation of the second kind. The advantage of the general Legendre wavelets gives a kind of fast algorithm for easy implementation. Using the general operational matrix and expression of an integral function Fredholm integral equation of the second kind is transformed into a system of algebraic equations by the general Legendre wavelets. Approximate solutions of Fredholm integral equation of the second kind are derived. The numerical examples demonstrate that the algorithm is valid.

2. Preliminaries.

2.1. **Definitions.** The general Legendre wavelets  $\psi_{km}(t)$ ,  $k = 1, 2, \dots, N$ ,  $m = 0, 1, \dots, M - 1$ , on the interval  $[a, b)$  are defined as

$$\psi_{km}(t) = \begin{cases} [(2m + 1)d_k^{-1}]^{\frac{1}{2}} L_m(d_k^{-1}(2t - t_{k-1} - t_k)), & t_{k-1} \leq t < t_k, \\ 0, & \text{otherwise,} \end{cases} \tag{1}$$

where  $t_0 = a$ ,  $t_N = b$  and  $d_k = t_k - t_{k-1}$ ,  $k = 1, 2, \dots, N$ . And  $L_m(t)$ ,  $m = 0, 1, \dots$ , are Legendre polynomials on the interval  $[-1, 1]$  given by the following recursive formula:

$$\begin{cases} L_0(t) = 1, & L_1(t) = t, \\ (m + 1)L_{m+1}(t) = (2m + 1)tL_m(t) - mL_{m-1}(t). \end{cases} \tag{2}$$

2.2. **Function approximation.** A vector function  $f(t)$  on the interval  $[a, b)$  is expressed as

$$f(t) \simeq \sum_{k=1}^N \sum_{m=0}^{M-1} f_{km} \psi_{km}(t), \tag{3}$$

where

$$f_{km} = [(2m + 1)d_k]^{\frac{1}{2}} 2^{-1} \int_{-1}^1 f(2^{-1}(d_k t + t_{k-1} + t_k)) L_m(t) dt.$$

Rewrite  $f(t)$  as

$$f(t) \simeq \sum_{k=1}^N F_k \Psi_k(t) = F \Psi(t), \tag{4}$$

where

$$F_k = [f_{k0}, \dots, f_{k,M-1}], \quad F = [F_1, \dots, F_N],$$

$$\Psi_k(t) = [\psi_{k0}(t), \dots, \psi_{k,M-1}(t)]^T, \quad \Psi(t) = [\Psi_1^T(t), \dots, \Psi_N^T(t)]^T.$$

For corresponding  $F_k$  and  $F$ , we denote

$$\hat{F}_k = [f_{k0}^T, \dots, f_{k,M-1}^T]^T, \quad \hat{F} = [\hat{F}_1^T, \dots, \hat{F}_N^T]^T,$$

where T is the transpose.

2.3. **Expression of an integral function.** Let a matrix function  $M(t)$  be appropriate to a vector function  $f(t)$ . We express  $M(t)$  and  $f(t)$ , respectively, as

$$M(t) \simeq \sum_{k=1}^N \sum_{m=0}^{M-1} M_{km} \psi_{km}(t), \quad f(t) \simeq \sum_{k=1}^N \sum_{m=0}^{M-1} f_{km} \psi_{km}(t).$$

Then,

$$M(t)f(t) \simeq \sum_{k=1}^N \sum_{i=0}^{M-1} \sum_{j=0}^{M-1} M_{ki} f_{kj} \psi_{ki}(t) \psi_{kj}(t).$$

From

$$\psi_{ki}(t) \psi_{kj}(t) \simeq \sum_{m=0}^{M-1} d_{km}^{(ij)} \psi_{km}(t),$$

where

$$d_{km}^{(ij)} = [(2i + 1)(2j + 1)(2m + 1)d_k^{-1}]^{\frac{1}{2}} 2^{-1} \int_{-1}^1 L_i(t) L_j(t) L_m(t) dt,$$

we have

$$M(t)f(t) \simeq \sum_{k=1}^N \sum_{m=0}^{M-1} \tilde{M}_{km} \psi_{km}(t) = \sum_{k=1}^N \tilde{M}_k \Psi_k(t), \tag{5}$$

where

$$\begin{aligned} \tilde{M}_{km} &= \hat{M}_{km} \hat{F}_k, \quad \hat{F}_k = [f_{k0}^T, \dots, f_{k,M-1}^T]^T, \quad \hat{M}_k = \hat{M}_k \hat{F}_k, \\ \hat{M}_k &= [\tilde{M}_{k0}^T, \dots, \tilde{M}_{k,M-1}^T]^T, \quad \tilde{M}_k = [\hat{M}_{k0}^T, \dots, \hat{M}_{k,M-1}^T]^T, \\ \hat{M}_{km} &= \left[ \sum_{i=0}^{M-1} d_{km}^{(i0)} M_{ki}, \dots, \sum_{i=0}^{M-1} d_{km}^{(i,M-1)} M_{ki} \right]. \end{aligned}$$

Therefore,

$$K(s, t)f(t) \simeq \sum_{k=1}^N \sum_{m=0}^{M-1} \tilde{K}_{km}(s) \psi_{km}(t), \tag{6}$$

where

$$\begin{aligned} \tilde{K}_{km}(s) &= \hat{K}_{km}(s) \hat{F}_k, \quad \hat{K}_{km}(s) = \left[ \sum_{i=0}^{M-1} d_{km}^{(i0)} K_{ki}(s), \dots, \sum_{i=0}^{M-1} d_{km}^{(i,M-1)} K_{ki}(s) \right], \\ K_{ki}(s) &= [(2i + 1)d_k]^{\frac{1}{2}} 2^{-1} \int_{-1}^1 K(s, 2^{-1}(d_k t + t_{k-1} + t_k)) L_i(t) dt. \end{aligned}$$

Let

$$\begin{aligned} g(t) &= \int_a^b K(t, s)f(s) ds \simeq \sum_{k=1}^N \sum_{m=0}^{M-1} g_{km} \psi_{km}(t), \tag{7} \\ \hat{K}_{km}(t) &\simeq \sum_{j=1}^N \sum_{l=0}^{M-1} \hat{K}_{km}^{(jl)} \psi_{jl}(t), \end{aligned}$$

where

$$\begin{aligned} \hat{K}_{km}^{(jl)} &= \left[ \sum_{i=0}^{M-1} d_{km}^{(i0)} K_{ki}^{(jl)}, \dots, \sum_{i=0}^{M-1} d_{km}^{(i,M-1)} K_{ki}^{(jl)} \right], \\ K_{ki}^{(jl)} &= [(2l + 1)d_j]^{\frac{1}{2}} 2^{-1} \int_{-1}^1 K_{ki}(2^{-1}(d_j t + t_{j-1} + t_j)) L_l(t) dt. \end{aligned}$$

By Equation (6), we have

$$g(t) \simeq \sum_{j=1}^N \sum_{l=0}^{M-1} \sum_{k=1}^N \sum_{m=0}^{M-1} \hat{K}_{km}^{(jl)} \left( \int_{t_{k-1}}^{t_k} \psi_{km}(t) dt \right) \hat{F}_k \psi_{jl}(t).$$

So,

$$\hat{G} = \sum_{i=1}^N \sum_{j=1}^N E_{ij}^{(N)} \otimes \sqrt{d_j} K_j^{(i)} \hat{F}, \tag{8}$$

where  $\hat{G}$  has the meaning similar to  $\hat{F}$ ,  $E_{ij}^{(N)}$  is the  $N \times N$  matrix with 1 at its entry  $(i, j)$  and zeros elsewhere,  $\otimes$  denotes Kronecker product and

$$K_j^{(i)} = \left[ K_{j0}^{(i0)T}, \dots, K_{j0}^{(i,M-1)T} \right]^T.$$

**3. Analysis of Fredholm Integral Equation of the Second Kind.** Now we consider the following Fredholm integral equation of the second kind:

$$A(t)x(t) = \lambda \int_a^b K(t, s)x(s)ds + B(t)u(t), \quad t \in [a, b], \tag{9}$$

where  $x(t)$  is an unknown  $l$ -dimensional function and  $u(t)$  a given  $r$ -dimensional function.  $A(t)$ ,  $K(t, s)$  and  $B(t)$  are given matrix functions of appropriate dimensions and  $\lambda$  a given constant. Suppose that Equation (9) has the unique solution. We express  $A(t)$ ,  $x(t)$ ,  $\int_a^b K(t, s)x(s)ds$ ,  $B(t)$  and  $u(t)$ , respectively. By Equations (5) and (6), we have

$$A(t)x(t) \simeq \sum_{k=1}^N \sum_{m=0}^{M-1} \tilde{A}_{km}h_{km}(t), \quad B(t)u(t) \simeq \sum_{k=1}^N \sum_{m=0}^{M-1} \tilde{B}_{km}h_{km}(t),$$

$$\int_a^b K(t, s)x(s)ds \simeq \sum_{k=1}^N \sum_{m=0}^{M-1} g_{km}h_{km}(t).$$

Substituting the above equations into Equation (9), we have

$$[\tilde{A}_1, \dots, \tilde{A}_N] = \lambda [G_1, \dots, G_N] + [\tilde{B}_1, \dots, \tilde{B}_N].$$

Rewrite the above equation as

$$[\hat{A}_1^T, \dots, \hat{A}_N^T]^T = \lambda [\hat{G}_1^T, \dots, \hat{G}_N^T]^T + [\hat{B}_1^T, \dots, \hat{B}_N^T]^T,$$

where

$$\hat{A}_k = [\tilde{A}_{k0}^T, \dots, \tilde{A}_{k,M-1}^T]^T,$$

$\hat{G}_N$  and  $\hat{B}_N$  have the similar meaning as  $\hat{A}_N$ . So,

$$\left[ (\hat{A}_1 \hat{X}_1)^T, \dots, (\hat{A}_N \hat{X}_N)^T \right]^T = \lambda \hat{G} + \left[ (\hat{B}_1 \hat{U}_1)^T, \dots, (\hat{B}_N \hat{U}_N)^T \right]^T.$$

Using Kronecker product  $\otimes$ , we have

$$\hat{X} = \left[ \sum_{k=1}^N (E_{kk}^{(N)} \otimes \hat{A}_k) - \lambda \sum_{i=1}^N \sum_{j=1}^N E_{ij}^{(N)} \otimes \sqrt{d_j} K_j^{(i)} \right]^{-1} \sum_{k=1}^N (E_{kk}^{(N)} \otimes \hat{B}_k) \hat{U}. \tag{10}$$

By the method in [11] an error estimation follows. Let  $\hat{x}_N^M(t)$  be an Legendre wavelets solution of Equation (9). Then,  $\hat{x}_N^M(t)$  satisfies

$$A(t)\hat{x}_N^M(t) = \lambda \int_a^b K(t, s)\hat{x}_N^M(s)ds + B(t)u(t) + r_N^M(t), \quad t \in [a, b], \tag{11}$$

where

$$r_N^M(t) = A(t)\hat{x}_N^M(t) - \lambda \int_a^b K(t, s)\hat{x}_N^M(s)ds - B(t)u(t).$$

Combining Equation (9) and Equation (11), we have

$$A(t) [x(t) - \hat{x}_N^M(t)] = \lambda \int_a^b K(t, s) [x(s) - \hat{x}_N^M(s)] ds - r_N^M(t), \quad t \in [a, b]. \tag{12}$$

We can solve Equation (12) as an estimation of the error function of this general Legendre wavelets method.

4. Example.

**Example 4.1.** In Equation (9), taking  $A(t) = 1$ ,  $\lambda = 1$ ,  $N(t) = t + s$ ,  $B(t) = 1$  and  $u(t) = e^t + (1 - e)t - 1$  yields the Fredholm integral equation of the second kind [11].

$$x(t) = \int_0^1 (t + s)x(s)ds + e^t + (1 - e)t - 1,$$

where  $x(t)$  is an 1-dimensional function.

By Equation (10) and choosing  $M = 4$  and  $N = 4$ , we have the Legendre wavelets solution  $\hat{x}_N^M(t)$ :

$$\begin{aligned} \hat{x}_N^M(t) = & \frac{985}{1734}\psi_{10}(t) + \frac{153}{3736}\psi_{11}(t) + \frac{45}{34061}\psi_{12}(t) + \frac{9}{322492}\psi_{13}(t) \\ & + \frac{1283}{1759}\psi_{20}(t) + \frac{412}{7835}\psi_{21}(t) + \frac{29}{17095}\psi_{22}(t) + \frac{3}{83719}\psi_{23}(t) \\ & + \frac{1801}{1923}\psi_{30}(t) + \frac{153}{2266}\psi_{31}(t) + \frac{78}{35809}\psi_{32}(t) + \frac{23}{499870}\psi_{33}(t) \\ & + \frac{469}{390}\psi_{40}(t) + \frac{189}{2180}\psi_{41}(t) + \frac{76}{27173}\psi_{42}(t) + \frac{20}{338521}\psi_{43}(t). \end{aligned}$$

We give the absolute errors in Table 1.

TABLE 1. Absolute errors  $|x(t) - \hat{x}_N^M(t)|$  (Example 4.1)

$t$	Legendre wavelets ( $M = 4, N = 4$ )	Legendre wavelets ( $M = 8, N = 4$ )	Hybrid Taylor [11] ( $M = 4, N = 4$ )	Hybrid Taylor [11] ( $M = 8, N = 4$ )
0.2	$0.1081 \times 10^{-5}$	$0.0710 \times 10^{-13}$	0.0021	$0.4918 \times 10^{-8}$
0.4	$0.0799 \times 10^{-5}$	$0.0133 \times 10^{-13}$	0.0027	$0.6380 \times 10^{-8}$
0.6	$0.0989 \times 10^{-5}$	$0.0244 \times 10^{-13}$	0.0034	$0.7793 \times 10^{-8}$
0.8	$0.2265 \times 10^{-5}$	$0.1554 \times 10^{-13}$	0.0040	$0.9199 \times 10^{-8}$
1.0	$0.5660 \times 10^{-5}$	$0.7149 \times 10^{-13}$	0.0043	$0.9780 \times 10^{-8}$

**Example 4.2.** Consider the Fredholm integral equation of the second kind described by

$$\begin{aligned} \begin{bmatrix} -2t^2e^{-t} & 1 \\ e^{-t} & -e^t \end{bmatrix} x(t) = \int_1^2 \begin{bmatrix} t^2 + s^2 & -t^2s \\ 1 & s \end{bmatrix} x(s)dt \\ + \begin{bmatrix} e^{-t} + (2e^{-1} + e - e^2 - 3e^{-2} - 2)t^2 + e - 2e^2 \\ 3e^{-2} - e^2 + e - 2e^{-1} \end{bmatrix}, \end{aligned}$$

where  $x(t)$  is a 2-dimensional vector function.

By Equation (10), we have the general Legendre wavelets solution  $\hat{x}_N^M(t) = [x_1(t), x_2(t)]^T$  for given natural numbers  $M$  and  $N$ . Table 2 shows the absolute errors.

**Example 4.3.** Consider the Fredholm integral equation of the second kind described by

$$\begin{aligned} \begin{bmatrix} -2t^2e^{t-1} & te^{\frac{2-t}{2}} & 2e^{\frac{1-2t}{2}} \\ -2e^{t-1} & 0 & 2t^2e^{\frac{1-2t}{2}} \\ -3e^{t-1} & -2e^{\frac{1-t}{2}} & t^2e^{1-t} \end{bmatrix} x(t) = \int_{\frac{1}{2}}^{\frac{5}{4}} \begin{bmatrix} t^2s & 1 & ts^2 \\ 2 & t^2 & 0 \\ 3 & s & t^2 + s^2 \end{bmatrix} x(s)ds \\ + \begin{bmatrix} \left(\frac{9}{4}e^{-\frac{5}{4}} - \frac{3}{2}e^{-\frac{1}{2}} - 2e^{-1}\right)t^2 + \left(e + \frac{5}{4}e^{\frac{1}{2}} - \frac{17}{16}e^{\frac{5}{4}}\right)t + 2\left(e^{\frac{1}{2}} - e^{\frac{5}{8}} + e^{\frac{1}{4}}\right) \\ 2\left(e^{\frac{1}{2}} - e^{\frac{5}{8}} + e^{\frac{1}{4}}\right)t^2 + 2\left(e^{-\frac{5}{4}} - e^{-\frac{1}{2}} - e^{-1}\right) \\ \left(e - e^{\frac{5}{4}} + e^{\frac{1}{2}}\right)t^2 + 3\left(e^{-\frac{5}{4}} - e^{-\frac{1}{2}} - e^{\frac{1}{4}} - e^{-1}\right) + \frac{3}{2}e^{\frac{5}{8}} - \frac{17}{16}e^{\frac{5}{4}} - \frac{3}{4}e^{\frac{1}{2}} \end{bmatrix} \end{aligned}$$

where  $x(t)$  is a 3-dimensional vector function.

By Equation (10), we have the general Legendre wavelets solution  $\hat{x}_N^M(t) = [x_1(t), x_2(t), x_3(t)]^T$  for given natural numbers  $M$  and  $N$ . The absolute errors can be seen in Table 2.

TABLE 2. Absolute errors  $\|x(t) - \hat{x}_N^M(t)\|_2$  of Legendre wavelets (Example 4.2)

$t$	$(M = 5, N = 4)$	$(M = 6, N = 4)$	$(M = 7, N = 4)$	$(M = 8, N = 4)$
1.0	$4.2193 \times 10^{-8}$	$2.4467 \times 10^{-9}$	$7.3681 \times 10^{-12}$	$3.0274 \times 10^{-13}$
1.2	$3.8362 \times 10^{-8}$	$3.7486 \times 10^{-10}$	$6.4495 \times 10^{-12}$	$4.7714 \times 10^{-14}$
1.4	$4.8673 \times 10^{-8}$	$3.9959 \times 10^{-10}$	$5.0930 \times 10^{-12}$	$3.0296 \times 10^{-14}$
1.6	$4.2650 \times 10^{-8}$	$7.4648 \times 10^{-11}$	$4.3933 \times 10^{-12}$	$3.7340 \times 10^{-14}$
1.8	$2.1266 \times 10^{-8}$	$3.1891 \times 10^{-10}$	$5.8080 \times 10^{-12}$	$8.0841 \times 10^{-14}$
2.0	$2.4361 \times 10^{-7}$	$1.7937 \times 10^{-9}$	$3.2462 \times 10^{-11}$	$9.0616 \times 10^{-14}$

TABLE 3. Absolute errors  $\|x(t) - \hat{x}_N^M(t)\|_2$  of Legendre wavelets (Example 4.3)

$t$	$(M = 5, N = 3)$	$(M = 6, N = 4)$	$(M = 7, N = 5)$	$(M = 8, N = 6)$
0.50	$1.0173 \times 10^{-7}$	$1.8112 \times 10^{-10}$	$5.9306 \times 10^{-13}$	$3.0364 \times 10^{-15}$
0.65	$4.1389 \times 10^{-7}$	$2.9341 \times 10^{-11}$	$8.6958 \times 10^{-13}$	$3.0947 \times 10^{-15}$
0.80	$3.7592 \times 10^{-7}$	$1.6537 \times 10^{-10}$	$3.2570 \times 10^{-12}$	$1.5067 \times 10^{-14}$
0.95	$5.0479 \times 10^{-7}$	$2.8982 \times 10^{-10}$	$7.7878 \times 10^{-13}$	$5.0378 \times 10^{-14}$
1.10	$1.7636 \times 10^{-7}$	$6.6399 \times 10^{-11}$	$1.7907 \times 10^{-13}$	$6.6354 \times 10^{-15}$
1.25	$3.6289 \times 10^{-7}$	$1.0490 \times 10^{-10}$	$5.9833 \times 10^{-13}$	$4.3203 \times 10^{-15}$

**5. Conclusion.** Using the general Legendre wavelets to solve Fredholm integral equation of the second kind has the advantages that the integration interval can be divided arbitrarily and series numbers can be chosen willfully. Applying the excellent properties of the general Legendre wavelets, the general algorithm for Fredholm integral equation of the second kind is derived. The results in Table 1 imply that the general Legendre wavelets solutions converge to the exact solution more rapidly than the hybrid Taylor solutions. Since it is not necessary to choose  $N$  as the power of 2, the present approach is more convenient for application on an arbitrary interval.

**Acknowledgements.** The authors would like to thank the anonymous referees for their useful comments and suggestions. The research was supported partially by National Natural Science Foundation of China (Grant Nos. 10871056 and 10971150) and by Science Research Foundation in Harbin Institute of Technology (Grant No. HITC200708).

## REFERENCES

- [1] Y. Chen, J. Li, B. Feng and W. Guan, Hermite cubic spline multi-wavelet natural boundary element method, *ICIC Express Letters*, vol.3, no.2, pp.213-218, 2009.
- [2] M. Razzaghi and S. Yousefi, Legendre wavelets method for constrained optimal control problems, *Mathematical Methods in the Applied Sciences*, vol.25, pp.529-539, 2002.
- [3] S. Yousefi and M. Razzaghi, Legendre wavelets method for the nonlinear Volterra-Fredholm integral equations, *Mathematics and Computers in Simulation*, vol.70, pp.1-8, 2005.
- [4] K. Maleknejad, S. Sohrabi and B. Baranji, Application of 2D-BPFs to nonlinear integral equations, *Communications in Nonlinear Science and Numerical Simulations*, vol.15, pp.527-535, 2010.
- [5] C. F. Chen and C. H. Hsiao, Walsh series analysis in optimal control, *Int. J. Control*, vol.21, pp.881-897, 1975.

- [6] N. S. Hsu and B. Chang, Analysis and optimal control of time-varying linear systems via block-pulse functions, *Int. J. Control*, vol.33, pp.1107-1122, 1989.
- [7] I. R. Horng and J. H. Chou, Analysis, parameter estimation and optimal control of time-delay systems via Chebyshev series, *Int. J. Control*, vol.41, pp.1221-1234, 1985.
- [8] C. Hwang and Y. P. Shih, Laguerre series direct method for variational problems, *J. Optimization Theory and Applications*, vol.39, pp.143-149, 1983.
- [9] H. Lee and F. C. Kung, Shifted Legendre series solution and parameter estimation of linear delayed systems, *Int. J. Systems Science*, vol.16, pp.1249-1256, 1985.
- [10] P. N. Parskevopoulos, P. D. Sparis and S. G. Mouroutsos, The Fourier series operational matrix of integration, *Int. J. Systems Science*, vol.16, pp.171-176, 1985.
- [11] K. Maleknejad and Y. Mahmoudi, Numerical solution of linear Fredholm integral equation by using hybrid Taylor and block-pulse functions, *Applied Mathematics and Computation*, vol.149, pp.799-806, 2004.
- [12] X. T. Wang, Numerical solution of optimal control for scaled systems by hybrid functions, *International Journal of Innovative Computing, Information and Control*, vol.4, no.4, pp.849-855, 2008.
- [13] X. T. Wang and C. S. Hong, Numerical solutions of neutral functional differential systems by hybrid of block-pulse functions and Chebyshev polynomials, *International Journal of Innovative Computing, Information and Control*, vol.5, no.10(A), pp.3201-3206, 2009.